

VSN240-MP MicroRadar™ Sensor for Parking

Extensive testing has shown that wireless magnetometer and infrared sensors are not the best solutions for static parking applications, as neither provides consistent parking data in all conditions. The magnetic nulls and electromagnetic interference can cause limitations for wireless sensors, and infrared sensors are susceptible to dirt or oil.

After years of research and development, and with multiple patents pending, Sensys Networks announces the ultimate solution for a wireless parking sensor: MicroRadar™.

	MicroRadar™	Magnetometer	InfraRed
Immunity from vehicles adjacent to empty space	✓	⊗	✓
Robust RF performance	✓	⊗	⊗
Ignores nearby double parked vehicles	✓	⊗	✓
Accommodates dirt, dust, or oil on sensor	✓	✓	⊗
Not vulnerable to electromagnetic interference	✓	⊗	✓
Consistent performance in all lighting conditions	✓	✓	⊗
Maintains state reliably during long-duration session	✓	⊗	✓
Unaffected by slow-moving queues of nearby vehicles	✓	⊗	✓

Sensys Networks MicroRadar™ incorporates an extremely low power, wide-band radar with a Sensys Networks Nano-Power Protocol radio. This compact in-ground sensor works on the same principle as any other radar. High frequency RF pulses are transmitted, bounced off a target object, and measured by a time-gated return RF mixer. RF reflections are analyzed to produce presence, distance, and motion measurements.

MicroRadar can precisely detect the onset of parking events and the clearance of cars from spaces. The radar is tuned for offset, minimum range, and maximum range based on installation configuration.



Features and Functions

Simple installation, long life

- Sensors install flush to pavement in about 10 minutes
- Eight year battery life

On-street, off-street, truck parking and top-deck applications

- Actively measures presence of vehicles
- Parameters for range and off-set optimize any configuration
- Differentiates between large and small, stationary and moving
- Retains state no matter how long the parking event
- Precisely measures start of parking and end of parking
- Differentiates between transient detections and parking events

Data for parking guidance and guided enforcement

- XML interfaces to parking guidance web sites and smart phone applications
 - Parkopedia, ParkMe
- SNAPS and Parking Session servers manage thousands of deployed sensors, archive data, and monitor system health
- Optional guided enforcement application
 - Supports Windows Mobile hand-held and Android tablets

Functional Specifications

Radio Specifications

over-the-air-protocol	Sensys Networks NanoPower (SNP) protocol (TDMA)
physical layer protocol	IEEE 802.15.4 PHY
modulation	Direct Sequence Spread Spectrum Offset Quadrature Phase-Shift Keying (DSSS O-QPSK)
transmit/receive bit rate	250 kbps
frequency band	2400 to 2483.5 MHz (ISM unlicensed band)
frequency channels	16
channel bandwidth	2 MHz
antenna type	ceramic patch antenna (mounted below top surface of sensor)
antenna field of view	±60° (azimuth & elevation)
nominal output power	+3 dBm
spurious emissions	<ul style="list-style-type: none"> 30 - 1000 MHz: < -56 dBm 1 - 12.75 GHz: < -44 dBm 1.8 - 1.9 GHz: < -56 dBm 5.15 - 5.3 GHz: < -51 dBm
typical receive sensitivity	-101 dBm

Radar Specifications

frequency	6.3 GHz
bandwidth	>500 MHz
radiated power	within FCC class B limits
maximum range	4' (1.2 m) to 10' (3 m) (selectable)
calibration	self calibrating
sample rate	1/2, 1, 2, 4, and 8Hz (selectable)

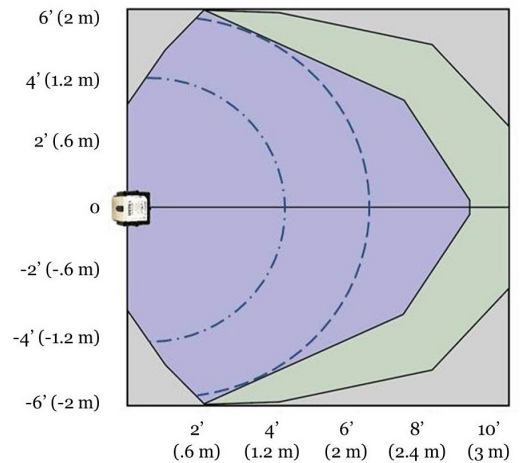
Power, Physical, & Environment

power supply	<ul style="list-style-type: none"> non-replaceable primary Li-SOCI23.6V battery pack 7.2 Ah (nominal capacity)
dimensions	2.9" x 2.9" x 2.3" (7.4 cm x 7.4 cm x 5.8 cm)
weight	0.6 pounds / 0.3 kg
environment	<ul style="list-style-type: none"> designed for mounting in-pavement or above ground/on a pole performance diminishes in standing water and in slushy conditions NEMA Type 6P enclosure IP67 ingress protection
operating temp	-40°F to 176° / -40°C to +85°C

Sensor Location Specification

<p>Single Car Parallel Parking: with Space Markings</p> <p>For a parallel parking space with pavement markings, measure 2' from the rear demarcation line and locate the sensor one-half of the width of the space from the curb. Direct the sensor toward the front of the space.</p>	<p>Parallel Parking: without Space Markings</p> <p>For a parallel parking space with no pavement markings measure out one-half of the width of the space from the curb and direct the sensor toward the front of the space. Locate each successive sensor 12' apart.</p>
<p>Diagonal Parking</p> <p>For diagonal parking into a space, measure 14' out from the passenger side demarcation line of the space and locate the sensor in the center of the space, measured perpendicular to the demarcation line. Direct the sensor toward the front of the space parallel to the demarcation lines.</p>	<p>Perpendicular Parking</p> <p>For perpendicular parking into a space, measure 14' out from the demarcated front of the space (curb or painted line) and locate the sensor in the center of the space. Direct the sensor toward the front of the space.</p>

In-Road Detection Zone



The purple and green areas depict sensor detection zones. The arcs represent range settings.

Compliance

safety	2006/95/EC
EMC	<ul style="list-style-type: none"> FCC: This device complies with Part 15 of the FCC rules. Operation is subject to the following two conditions: (1) This device may not cause harmful interference, and (2) this device must accept any interference received, including interference that may cause undesired operation. 2004/108/EC

Local Distributor